

# Space Technology

## Attitude Control

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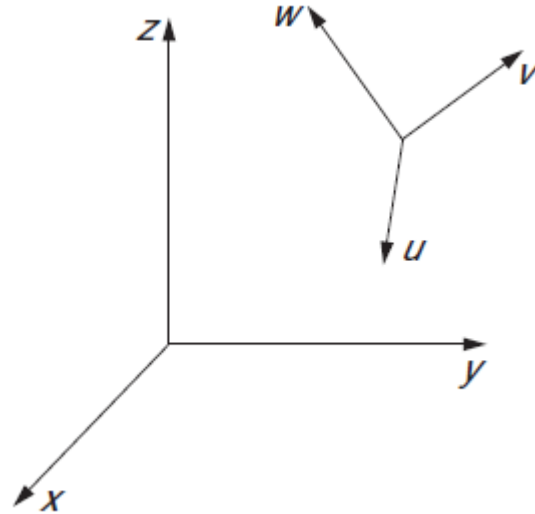


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# The attitude control system (ACS)

Determines and controls the orientation of the spacecraft (not orbit control!)

Attitude: the angular deviation of two coordinate systems (reference system/body system)



References:

- stars
- geocentric
- spacecraft mass centre

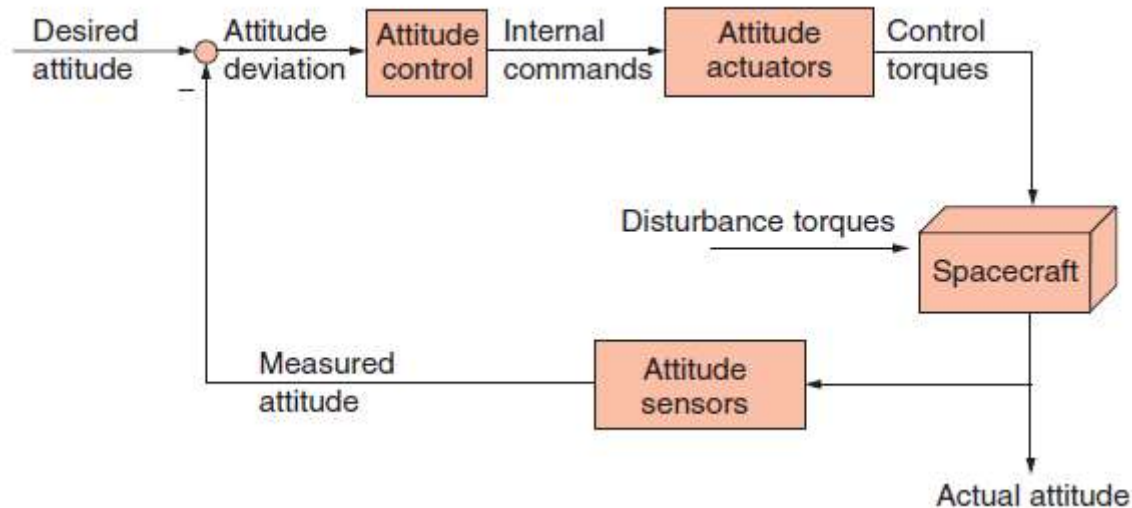
- Measures and determines the actual attitude [gyroscope](#) and [gimbals](#)
- Compares with the desired attitude
- Drives the actuators in order to achieve the desired attitude
  - Passive attitude control: steering of the attitude without the use of actuators
  - Active attitude control: actuators are used within a control loop
- Accuracy, stability and speed requirements (+cost, +lifetime)

# Source of disturbances

- ❑ Internal torques: actuators and moveable mechanisms
- ❑ External torques: interaction with the space environment
  - ❑ Gravity gradient (e.g. Earth)
  - ❑ Solar radiation pressure (geometry dependent)
  - ❑ Aerodynamic torque (atmosphere, LEO orbit)
  - ❑ Earth's magnetic field
  - ❑ Others: fuel leakage, [crew movement](#), etc.

# Attitude determination and control

1. Calculate the actual satellite attitude (three-axis attitude)
2. Active modification of the satellite's attitude

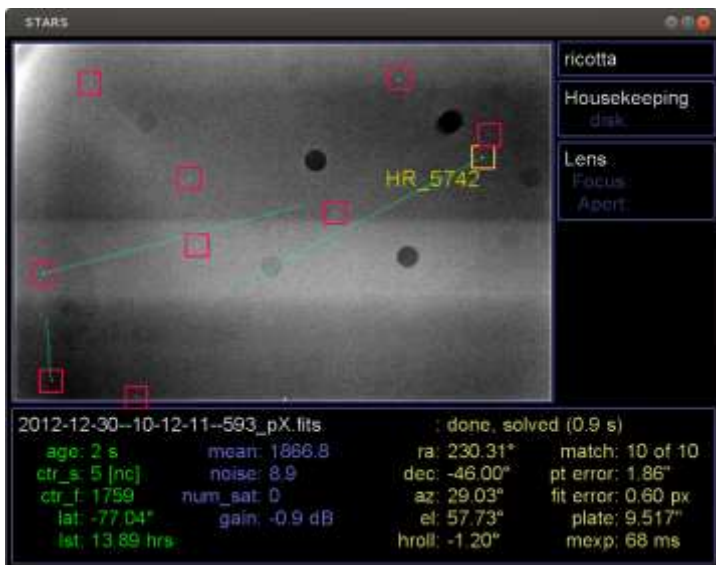
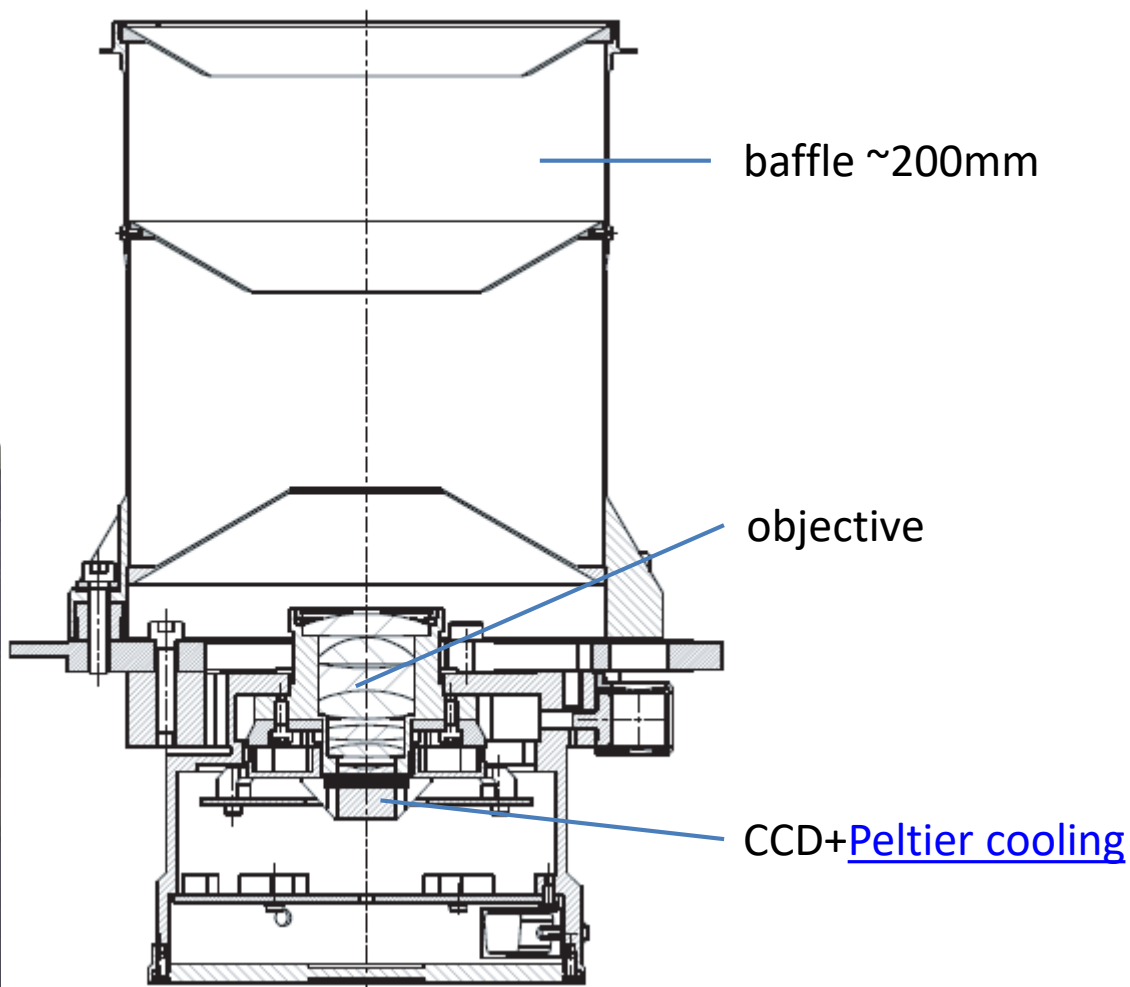


# Sensing the attitude – Star sensors

- ❑ Identification of star patterns
  - ❑ camera (sensor head)
  - ❑ electronics for image processing and attitude determination

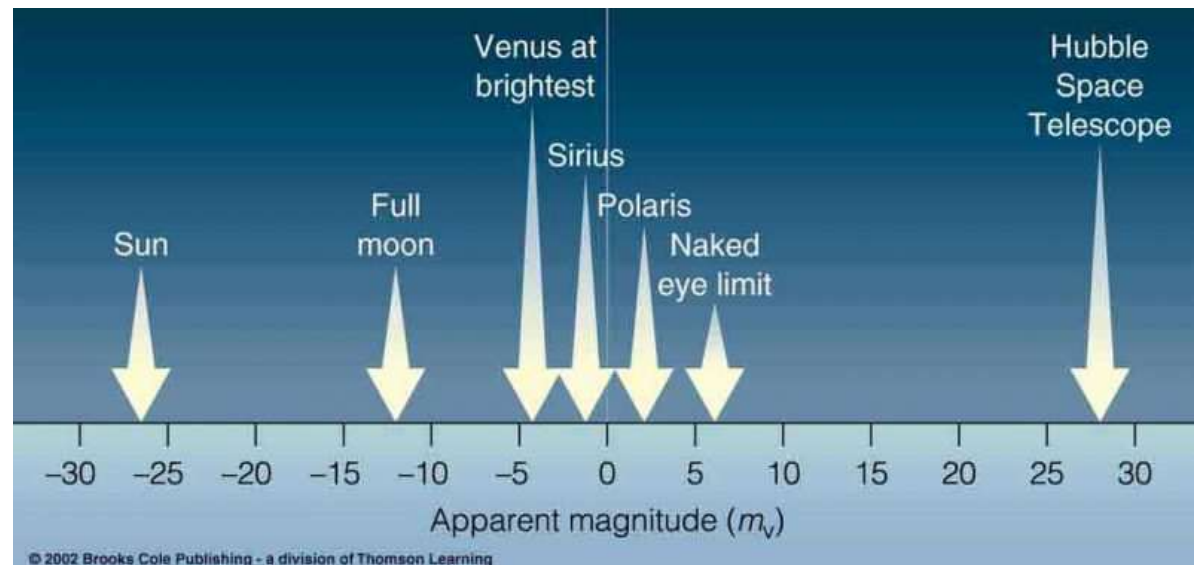
- ❑ Parameters:

- accuracy (1-5")
- signal strength
- # of processed stars



# Alphasat TDP#6: Star tracker

- ❑ Determine the location and attitude of a satellite
- ❑ Analyse the placement of the surrounding stars relative to the payload
- ❑ Operating conditions:  $-30^{\circ}\text{C}$  /  $60^{\circ}\text{C}$
- ❑ View:  $20^{\circ}$ ; min. magnitude: 5.8; accuracy: 4.3/26 arcsec for the xy/z axes;  $1024 \times 1024$
- ❑ A catalogue of over 3000 stars for guiding purposes
- ❑ [Active pixel detector system](#) (ASTRO APS) the most advanced radiation-resistant detection technology for long-term missions.

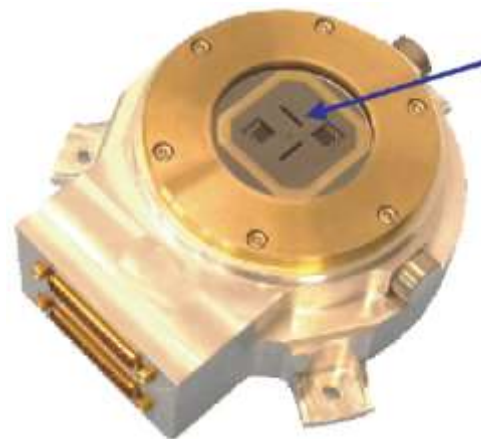
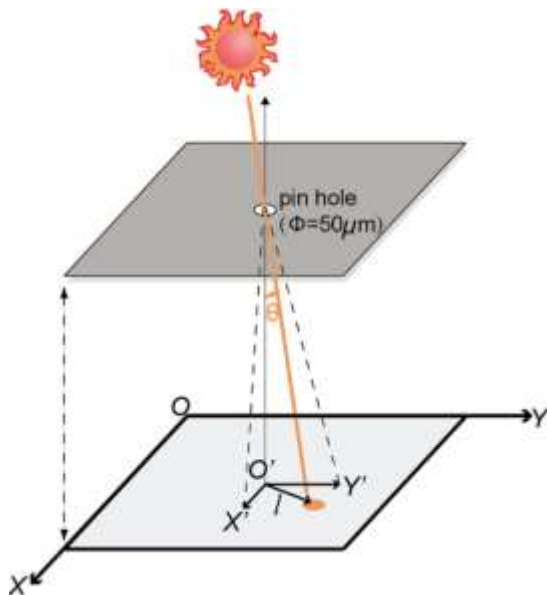


# Sensing the attitude – Sun sensors

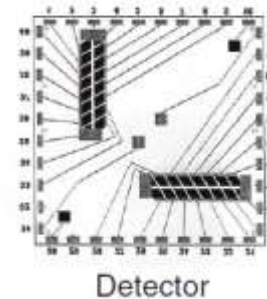
- ❑ Two-axis direction information
  - ❑ coarse (10-20°): comparison of the currents generated by the different cells



- ❑ fine sensors (0.01°): baffles/slots + photocells or CCD chips



Slots to avoid diffuse light

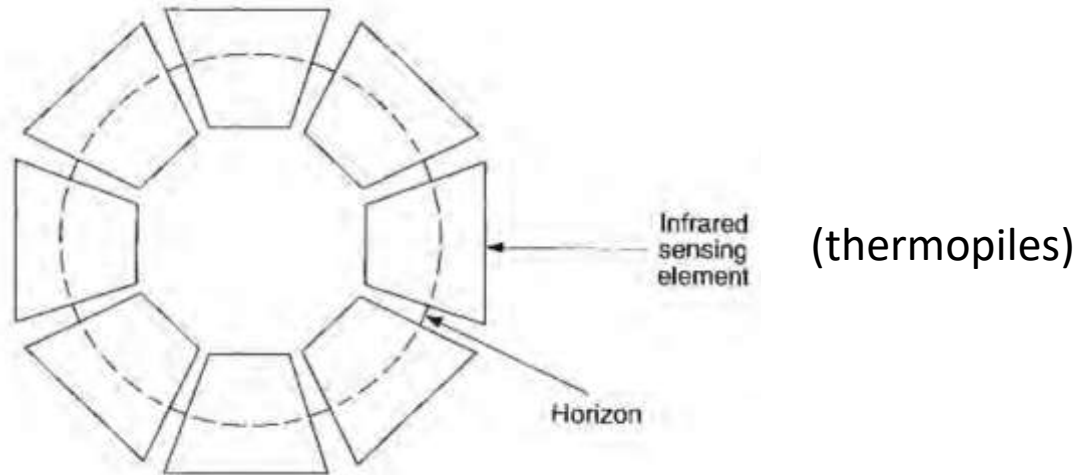


# Sensing the attitude – Earth sensors

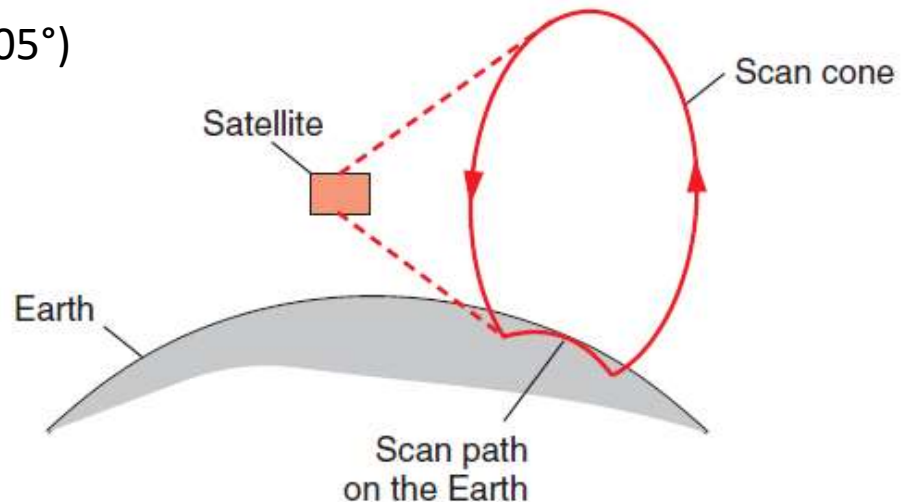
- ❑ They detect the Earth's horizon based on thermal infrared spectrum sensing: temperature dependency exists!
  - ❑ static ( $1^\circ$ )



Germanium lenses



- ❑ scanning (rotating mirror), ( $0.05^\circ$ )

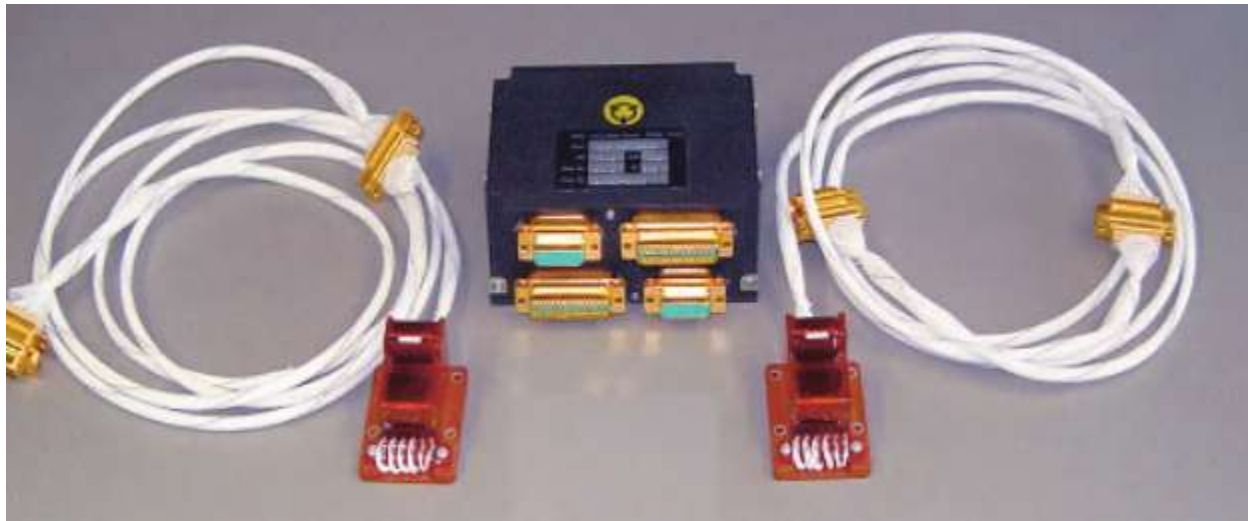




# Sensing the attitude – Magnetometers

- ❑ Measurement of the Earth's magnetic field (0.1-1° direction precision)
- ❑ [Coil-magnetic field-torque](#)

electronics



sensor heads

# Sensing the attitude – Gyroscopes

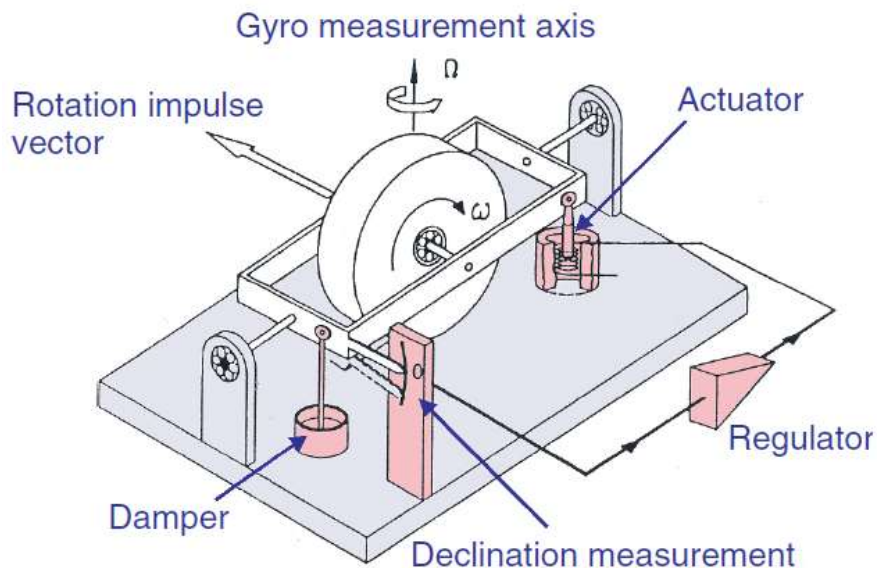
- ❑ Measure rotations in an inertial reference frame
- ❑ Independence from external sources
- ❑ Useful also for stabilizing spacecraft rotation
- ❑ Types:

Mechanical

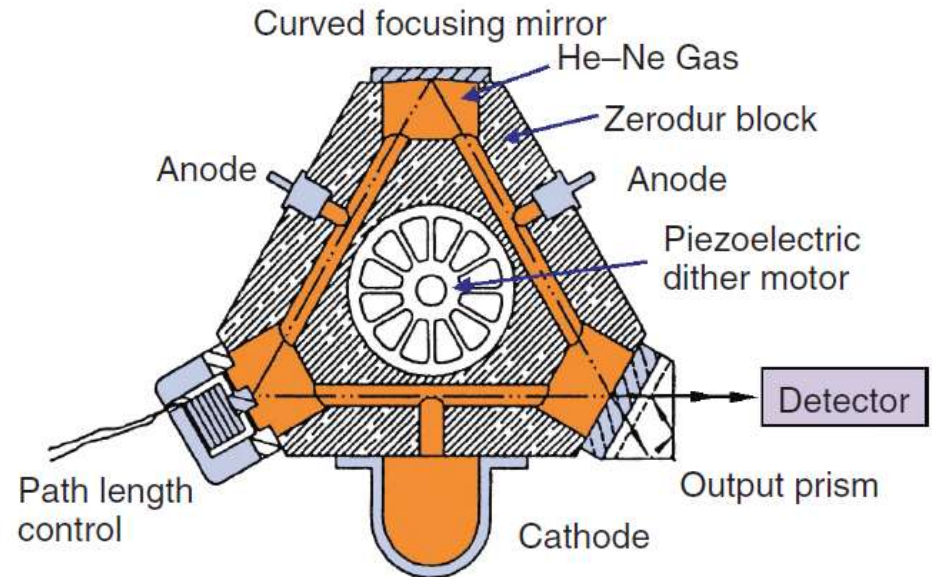
Hemispheric resonator (deformation due rotation)

Ring laser

Fiber optic



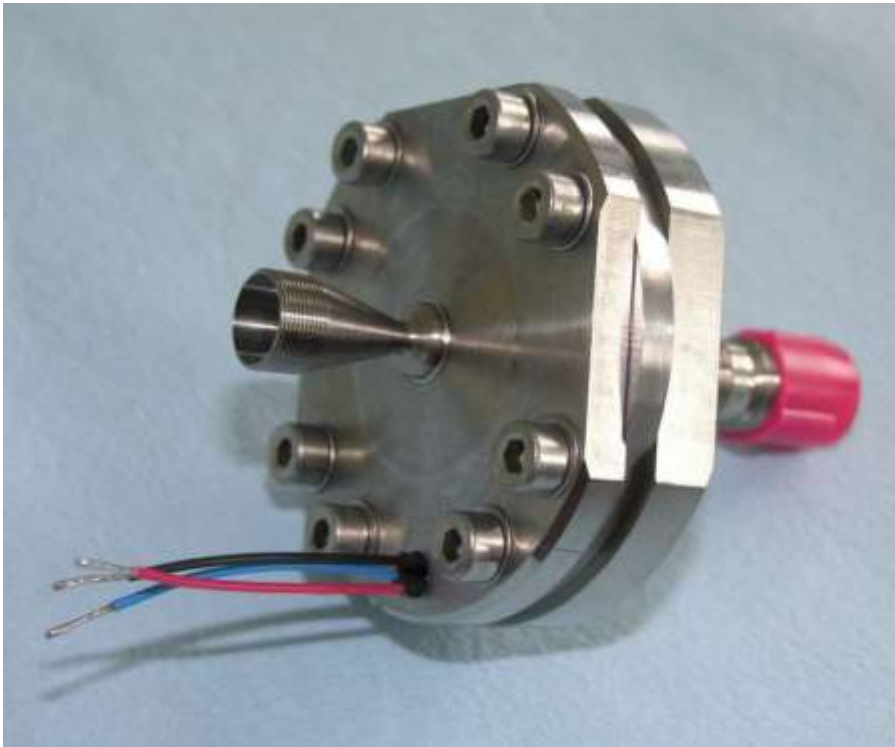
*Mechanical gyro*



*Ring laser gyro (interference; relativistic)*

# Actuators for attitude control 1.

- ❑ The spacecraft can be moved only by torque
- ❑ A torque changes the angular momentum
- ❑ External torque: cold gas thruster



- 0.1-10Nm torque level

# Actuators for attitude control 2.

- ❑ External torque: magnetic torquer
- ❑ A strong magnetic dipole that interacts with the Earth's magnetic field
- ❑ Weak: 75-10000 $\mu$ Nm



# Actuators for attitude control 3.

- ❑ Internal torque:
  - ❑ Rotational acceleration or deceleration of a flywheel
  - ❑ Rotation is driven by an electric motor which allows a variable torque
  - ❑ 0.1-250Nm
  
- ❑ reaction wheel
  - ❑ Designed for high torque provided at low rotation speeds
  - ❑ bidirectional
  
- ❑ **momentum wheel**
  - ❑ running constantly at high speed
  - ❑ single direction



# Actuators for attitude control 4.

- ❑ Internal torque:
  - ❑ Control Momentum Gyro (CMG; a gimbaled wheel)
- ❑ 100 times higher than the usual reaction torques of a reaction wheel
- ❑ CMG technology requires more volume and mass: preferably used in large satellites



- ❑ For complete three-axis attitude control at least three single-gimbal GMGs are needed

## Sources:

- ❑ Gary D. Gordon, Walter L. Morgan:  
Principles of Communications Satellites  
Wiley, ISBN: 978-0-471-55796-8
- ❑ Wilfried Ley, Klaus Wittmann and Willi Hallmann (ed):  
Handbook of Space Technology  
Wiley, ISBN: 978-0-470-69739-9

# Main topics / questions

- The role of the attitude control system**
- Disturbance sources**
- Attitude sensor types**
- Actuators for attitude control**